

NAG C Library Function Document

nag_real_sym_posdef_lin_solve (f04bdc)

1 Purpose

nag_real_sym_posdef_lin_solve (f04bdc) computes the solution to a real system of linear equations $AX = B$, where A is an n by n symmetric positive-definite matrix and X and B are n by r matrices. An estimate of the condition number of A and an error bound for the computed solution are also returned.

2 Specification

```
#include <nag.h>
#include <nagf04.h>

void nag_real_sym_posdef_lin_solve (Nag_OrderType order, Nag_UploType uplo,
    Integer n, Integer nrhs, double a[], Integer pda, double b[], Integer pdb,
    double *rcond, double *errbnd, NagError *fail)
```

3 Description

The Cholesky factorization is used to factor A as $A = U^T U$, if **uplo** = **Nag_Upper**, or $A = LL^T$, if **uplo** = **Nag_Lower**, where U is an upper triangular matrix and L is a lower triangular matrix. The factored form of A is then used to solve the system of equations $AX = B$.

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

Higham N J (2002) *Accuracy and Stability of Numerical Algorithms* (2nd Edition) SIAM, Philadelphia

5 Arguments

- 1: **order** – Nag_OrderType *Input*
On entry: the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = **Nag_RowMajor**. See Section 2.2.1.4 of the Essential Introduction for a more detailed explanation of the use of this argument.
Constraint: **order** = **Nag_RowMajor** or **Nag_ColMajor**.
- 2: **uplo** – Nag_UploType *Input*
On entry: if **uplo** = **Nag_Upper**, the upper triangle of the matrix A is stored.
 If **uplo** = **Nag_Lower**, the lower triangle of the matrix A is stored.
Constraint: **uplo** = **Nag_Upper** or **Nag_Lower**.
- 3: **n** – Integer *Input*
On entry: the number of linear equations n , i.e., the order of the matrix A .
Constraint: **n** ≥ 0 .

- 4: **nrhs** – Integer *Input*
On entry: the number of right-hand sides r , i.e., the number of columns of the matrix B .
Constraint: **nrhs** ≥ 0 .
- 5: **a**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **a** must be at least $\max(1, \mathbf{pda} \times \mathbf{n})$.
If **order** = **Nag_ColMajor**, the (i,j) th element of the matrix A is stored in **a**[($j-1$) $\times$ **pda** + $i-1$].
If **order** = **Nag_RowMajor**, the (i,j) th element of the matrix A is stored in **a**[($i-1$) $\times$ **pda** + $j-1$].
On entry: the n by n symmetric matrix A .
If **uplo** = **Nag_Upper**, the leading n by n upper triangular part of **a** contains the upper triangular part of the matrix A , and the strictly lower triangular part of **a** is not referenced.
If **uplo** = **Nag_Lower**, the leading n by n lower triangular part of **a** contains the lower triangular part of the matrix A , and the strictly upper triangular part of **a** is not referenced.
On exit: if **fail.code** = **NE_NOERROR** or **NE_RCOND**, the factor U or L from the Cholesky factorization $A = U^T U$ or $A = LL^T$.
- 6: **pda** – Integer *Input*
On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **a**.
Constraint: **pda** $\geq \max(1, \mathbf{n})$.
- 7: **b**[*dim*] – double *Input/Output*
Note: the dimension, *dim*, of the array **b** must be at least
 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$ when **order** = **Nag_ColMajor**;
 $\max(1, \mathbf{pdb} \times \mathbf{n})$ when **order** = **Nag_RowMajor**.
If **order** = **Nag_ColMajor**, the (i,j) th element of the matrix B is stored in **b**[($j-1$) $\times$ **pdb** + $i-1$].
If **order** = **Nag_RowMajor**, the (i,j) th element of the matrix B is stored in **b**[($i-1$) $\times$ **pdb** + $j-1$].
On entry: the n by r matrix of right-hand sides B .
On exit: if **fail.code** = **NE_NOERROR** or **NE_RCOND**, the n by r solution matrix X .
- 8: **pdb** – Integer *Input*
On entry: the stride separating matrix row or column elements (depending on the value of **order**) in the array **b**.
Constraints:
if **order** = **Nag_ColMajor**, **pdb** $\geq \max(1, \mathbf{n})$;
if **order** = **Nag_RowMajor**, **pdb** $\geq \max(1, \mathbf{nrhs})$.
- 9: **rcond** – double * *Output*
On exit: if **fail.code** = **NE_NOERROR** or **NE_RCOND**, an estimate of the reciprocal of the condition number of the matrix A , computed as $\mathbf{rcond} = 1 / (\|A\|_1 \|A^{-1}\|_1)$.
- 10: **errbnd** – double * *Output*
On exit: if **fail.code** = **NE_NOERROR** or **NE_RCOND**, an estimate of the forward error bound for a computed solution $\hat{x}$, such that $\|\hat{x} - x\|_1 / \|x\|_1 \leq \mathbf{errbnd}$, where $\hat{x}$ is a column of the computed solution returned in the array **b** and x is the corresponding column of the exact solution X . If **rcond** is less than *machine precision*, then **errbnd** is returned as unity.

11: **fail** – NagError *

Input/Output

The NAG error argument (see Section 2.6 of the Essential Introduction).

6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_BAD_PARAM

On entry, argument $\langle value \rangle$ had an illegal value.

NE_INT

On entry, **n** = $\langle value \rangle$.

Constraint: **n** ≥ 0 .

On entry, **nrhs** = $\langle value \rangle$.

Constraint: **nrhs** ≥ 0 .

On entry, **pda** = $\langle value \rangle$.

Constraint: **pda** > 0 .

On entry, **pdb** = $\langle value \rangle$.

Constraint: **pdb** > 0 .

NE_INT_2

On entry, **pda** = $\langle value \rangle$, **n** = $\langle value \rangle$.

Constraint: **pda** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$, **n** = $\langle value \rangle$. Constraint: **pdb** $\geq \max(1, \mathbf{n})$.

On entry, **pdb** = $\langle value \rangle$, **nrhs** = $\langle value \rangle$.

Constraint: **pdb** $\geq \max(1, \mathbf{nrhs})$.

NE_INTERNAL_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

NE_POS_DEF

The principal minor of order $\langle value \rangle$ of the matrix A is not positive-definite. The factorization has not been completed and the solution could not be computed.

NE_RCOND

A solution has been computed, but **rcond** is less than *machine precision* so that the matrix A is numerically singular.

7 Accuracy

The computed solution for a single right-hand side, $\hat{x}$, satisfies an equation of the form

$$(A + E)\hat{x} = b,$$

where

$$\|E\|_1 = O(\epsilon)\|A\|_1$$

and ϵ is the *machine precision*. An approximate error bound for the computed solution is given by

$$\frac{\|\hat{x} - x\|_1}{\|x\|_1} \leq \kappa(A) \frac{\|E\|_1}{\|A\|_1},$$

where $\kappa(A) = \|A^{-1}\|_1 \|A\|_1$, the condition number of A with respect to the solution of the linear equations. `nag_real_sym_posdef_lin_solve` (f04bdc) uses the approximation $\|E\|_1 = \epsilon \|A\|_1$ to estimate **errbnd**. See Section 4.4 of Anderson *et al.* (1999) for further details.

8 Further Comments

The total number of floating-point operations required to solve the equations $AX = B$ is proportional to $(\frac{1}{3}n^3 + n^2r)$. The condition number estimation typically requires between four and five solves and never more than eleven solves, following the factorization.

In practice the condition number estimator is very reliable, but it can underestimate the true condition number; see Section 15.3 of Higham (2002) for further details.

The complex analogue of `nag_real_sym_posdef_lin_solve` (f04bdc) is `nag_herm_posdef_lin_solve` (f04cdc).

9 Example

To solve the equations

$$AX = B,$$

where A is the symmetric positive-definite matrix

$$A = \begin{pmatrix} 4.16 & -3.12 & 0.56 & -0.10 \\ -3.12 & 5.03 & -0.83 & 1.18 \\ 0.56 & -0.83 & 0.76 & 0.34 \\ -0.10 & 1.18 & 0.34 & 1.18 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 8.70 & 8.30 \\ -13.35 & 2.13 \\ 1.89 & 1.61 \\ -4.14 & 5.00 \end{pmatrix}.$$

An estimate of the condition number of A and an approximate error bound for the computed solutions are also printed.

9.1 Program Text

```
/* nag_real_sym_posdef_lin_solve (f04bdc) Example Program.
 *
 * Copyright 2004 Numerical Algorithms Group.
 *
 * Mark 8, 2004.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagf04.h>
#include <nagx04.h>

int main(void)
{
    /* Scalars */
    double errbnd, rcond;
    Integer exit_status, i, j, n, nrhs, pda, pdb;

    /* Arrays */
    char uplo[2];
    double *a=0, *b=0;

    /* Nag Types */
    NagError fail;
    Nag_OrderType order;
```

```

    Nag_UploType uplo_enum;

#ifdef NAG_COLUMN_MAJOR
#define A(I,J) a[(J-1)*pda + I - 1]
#define B(I,J) b[(J-1)*pdb + I - 1]
    order = Nag_ColMajor;
#else
#define A(I,J) a[(I-1)*pda + J - 1]
#define B(I,J) b[(I-1)*pdb + J - 1]
    order = Nag_RowMajor;
#endif

    exit_status = 0;
    INIT_FAIL(fail);
    Vprintf("nag_real_sym_posdef_lin_solve (f04bdc) Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[\n] ");

    Vscanf("%ld%ld%*[\n] ", &n, &nrhs);
    if (n >= 0 && nrhs >= 0)
    {
        /* Allocate memory */
        if ( !(a = NAG_ALLOC(n*n, double)) ||
            !(b = NAG_ALLOC(n*nrhs, double)) )
        {
            Vprintf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
    }
#ifdef NAG_COLUMN_MAJOR
    pda = n;
    pdb = n;
#else
    pda = n;
    pdb = nrhs;
#endif
    }
    else
    {
        Vprintf("%s\n", "n and/or nrhs too small");
        exit_status = 1;
        return exit_status;
    }

    Vscanf(" ' %ls '%*[\n] ", uplo);
    if (*(unsigned char *)uplo == 'L')
        uplo_enum = Nag_Lower;
    else if (*(unsigned char *)uplo == 'U')
        uplo_enum = Nag_Upper;
    else
    {
        Vprintf("Unrecognised character for Nag_UploType type\n");
        exit_status = -1;
        goto END;
    }

    if (uplo_enum == Nag_Upper)
    {
        /* Read the upper triangular part of A from data file */
        for (i = 1; i <= n; ++i)
        {
            for (j = i; j <= n; ++j)
            {
                Vscanf("%lf", &A(i,j));
            }
        }
        Vscanf("%*[\n] ");
    }
    else

```

```

{
    /* Read the lower triangular part of A from data file */
    for (i = 1; i <= n; ++i)
    {
        for (j = 1; j <= i; ++j)
        {
            Vscanf("%lf", &A(i,j));
        }
    }
    Vscanf("%*[\n] ");
}

/* Read B from data file */
for (i = 1; i <= n; ++i)
{
    for (j = 1; j <= nrhs; ++j)
    {
        Vscanf("%lf", &B(i,j));
    }
}
Vscanf("%*[\n] ");

/* Solve the equations AX = B for X */

/* nag_real_sym_posdef_lin_solve (f04bdc).
 * Computes the solution and error-bound to a real symmetric
 * positive-definite system of linear equations
 */
nag_real_sym_posdef_lin_solve(order, uplo_enum, n, nrhs, a, pda, b, pdb,
                              &rcond, &errbnd, &fail);
if (fail.code == NE_NOERROR)
{
    /* Print solution, estimate of condition number and approximate */
    /* error bound */

    /* nag_gen_real_mat_print (x04cac).
     * Print real general matrix (easy-to-use)
     */
    nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs,
                           b, pdb, "Solution", 0, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from nag_gen_real_mat_print (x04cac).\n%s\n",
                fail.message);
        exit_status = 1;
        goto END;
    }
    Vprintf("\n");
    Vprintf("%s\n%6s%9.1e\n", "Estimate of condition number", "", 1.0/rcond);
    Vprintf("\n\n");

    Vprintf("%s\n%6s%9.1e\n\n", "Estimate of error bound for computed"
            " solutions", "", errbnd);
}
else if (fail.code == NE_RCOND)
{
    /* Matrix A is numerically singular. Print estimate of */
    /* reciprocal of condition number and solution */

    Vprintf("\n%s\n%6s%9.1e\n\n\n",
            "Estimate of reciprocal of condition number", "", rcond);
    /* nag_gen_real_mat_print (x04cac), see above. */
    nag_gen_real_mat_print(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n, nrhs,
                           b, pdb, "Solution", 0, &fail);
    if (fail.code != NE_NOERROR)
    {
        Vprintf("Error from nag_gen_real_mat_print (x04cac).\n%s\n",
                fail.message);
        exit_status = 1;
    }
}

```

```

        goto END;
    }
}
else if (fail.code == NE_POS_DEF)
{
    /* The matrix A is not positive definite to working precision */
    Vprintf("%s%3ld%s\n\n", "The leading minor of order ",
            fail.errnum, " is not positive definite");
}
END:
if (a) NAG_FREE(a);
if (b) NAG_FREE(b);

return exit_status;
}
#undef B
#undef A

```

9.2 Program Data

nag_real_sym_posdef_lin_solve (f04bdc) Example Program Data

```

    4      2                      :Values of N and NRHS
    'U'                      :Value of UPLO
    4.16  -3.12   0.56  -0.10
           5.03  -0.83   1.18
                0.76   0.34
                   1.18 :End of matrix A

    8.70   8.30
   -13.35   2.13
    1.89   1.61
   -4.14   5.00          :End of matrix B

```

9.3 Program Results

nag_real_sym_posdef_lin_solve (f04bdc) Example Program Results

Solution

```

           1      2
    1      1.0000   4.0000
    2     -1.0000   3.0000
    3      2.0000   2.0000
    4     -3.0000   1.0000

```

Estimate of condition number
9.7e+01

Estimate of error bound for computed solutions
1.1e-14
